

## TIMELIKE CURVES OF CONSTANT SLOPE IN MINKOWSKI SPACE $E_1^4$

Hüseyin KOCA YİĞİT, Mehmet ÖNDER

*Celal Bayar University, Faculty of Science and Art, Department of  
Mathematics, 45047 Manisa, Turkey, e-mail: mehmet.onder@bayar.edu.tr*

### ABSTRACT

In this paper, we will give some characterizations for timelike curves of constant slope in Minkowski space-time  $E_1^4$ .

**Key Words:** *Timelike curve, timelike vector, Minkowski space-time, curve of constant slope.*

### ÖZET

Bu çalışmada,  $E_1^4$  Minkowski 4-uzayındaki sabit eğimli timelike eğriler için bazı karakterizasyonları vereceğiz.

### 1. INTRODUCTION

Minkowski space-time  $E_1^4$  is an Euclidean space  $E^4$  provided with the standard flat metric given by

$$g = -dx_1^2 + dx_2^2 + dx_3^2 + dx_4^2$$

where  $(x_1, x_2, x_3, x_4)$  is a rectangular coordinate system in  $E_1^4$ .

Since  $g$  is an indefinite metric, recall that a vector  $v \in E_1^4$  can have one of three causal characters: it can be spacelike if  $g(v, v) > 0$  or  $v = 0$ , timelike if  $g(v, v) < 0$  and null(lightlike) if  $g(v, v) = 0$  and  $v \neq 0$ . Similarly, an arbitrary curve  $x(s)$  in  $E_1^4$  can locally be spacelike, timelike or null (lightlike), if all of its velocity vectors  $\alpha'(s)$  are respectively spacelike, timelike or null (lightlike). Also recall that the pseudo-norm of an arbitrary vector  $v \in E_1^4$  is given by  $\|v\| = \sqrt{|g(v, v)|}$ . Therefore  $\alpha$  is a unit vector if

$g(v, v) = \pm 1$ . The velocity of the curve  $x(s)$  is given by  $\|x'(s)\|$ . Next, vectors  $v, w$  in  $E_1^4$  are said to be orthogonal if  $g(v, w) = 0$ .

Let  $e = (0, 0, 0, 1) \in E_1^4$ . A timelike vector  $v = (v_1, v_2, v_3, v_4)$  is called *future pointing* (resp. *past pointing*) if  $g(v, e) < 0$  (resp.  $g(v, e) > 0$ ). Thus, a timelike vector  $v = (v_1, v_2, v_3, v_4)$  is future pointing if and only if  $v_2^2 + v_3^2 + v_4^2 < v_1^2$  and  $v_1^2 > 0$ . Let  $v$  be a future pointing (or past pointing) timelike unit vector, also  $y$  be a future pointing (or past pointing) timelike unit vector. If the angle between  $v$  and  $y$  is  $\theta \geq 0$  then we have

$$g(v, y) = -\cosh \theta,$$

and  $\theta \in \mathbb{R}$  is called *hyperbolic angle*. Let  $x$  be a spacelike unit vector. Then the angle  $\theta \geq 0$  between  $x$  and  $y$  is given by

$$g(x, y) = \sinh \theta,$$

and  $\theta \in \mathbb{R}$  is called *Lorentzian timelike angle*.

Denote by  $\{T(s), N(s), B_1(s), B_2(s)\}$  the moving Frenet frame along the curve  $x(s)$  in the space  $E_1^4$ . Then  $T, N, B_1, B_2$  are the tangent, the principal normal, the first binormal and the second binormal fields, respectively. A timelike (spacelike) curve  $x(s)$  is said to be parameterized by a pseudo-arclength parameter  $s$ , i.e.  $g(x'(s), x'(s)) = -1$  ( $g(x'(s), x'(s)) = 1$ ). In particular, a null curve  $x(s)$  in  $E_1^4$  is parameterized by a pseudo-arclength parameter  $s$ , if  $g(x''(s), x''(s)) = 1$  where pseudo-arclength function  $s$  is defined as follows in [1]

$$s = \int_0^t (g(x''(t), x''(t)))^{1/4} dt.$$

Let  $x(s)$  be a curve in Minkowski space-time  $E_1^4$ , parameterized by arclength function of  $s$ . Then for the timelike curve  $x(s)$  the following Frenet equations are given in [8]:

$$\begin{bmatrix} T' \\ N' \\ B_1' \\ B_2' \end{bmatrix} = \begin{bmatrix} 0 & k_1 & 0 & 0 \\ k_1 & 0 & k_2 & 0 \\ 0 & -k_2 & 0 & k_3 \\ 0 & 0 & -k_3 & 0 \end{bmatrix} \begin{bmatrix} T \\ N \\ B_1 \\ B_2 \end{bmatrix}$$

where  $T, N, B_1, B_2$  are mutually orthogonal vectors satisfying equations

$$g(T, T) = -1, g(N, N) = g(B_1, B_1) = g(B_2, B_2) = 1.$$

Recall the functions  $k_1 = k_1(s)$ ,  $k_2 = k_2(s)$  and  $k_3 = k_3(s)$  are called respectively, the first, the second and the third curvature of curve  $x(s)$ .

In Euclidean space  $E^4$ , a regular curve  $x(s)$  is a curve of constant slope or a helix provided the unit tangent  $T$  of  $x(s)$  has a constant angle  $\theta$  with some fixed line  $l$  directed in the unit vector  $U$ ; that is  $g(T, U) = \cos \theta$ . The condition for a curve to be a constant slope in Euclidean space  $E^4$  is usually given in the form

$$\frac{k_1^2}{k_2^2} + \left[ \frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) \right]^2 = \tan^2 \theta = \text{constant}, \quad (1)$$

where  $k_1, k_2$  and  $k_3$  are first, second and third curvatures of Euclidean curve  $\alpha(s)$ , respectively[3].

Clearly, (1) has a meaning only if  $k_1, k_2$  and  $k_3$  are nowhere zero, and it is only under this precondition that (1) is a necessary and sufficient condition for a curve of constant slope or helix.

In this study we give the timelike curves of constant slope whose unit tangent  $T$  has a constant hyperbolic angle  $\theta$  with some fixed timelike line  $l$  directed in the timelike unit vector  $U$ .

## 2. TIMELIKE CURVES OF CONSTANT SLOPE

**Theorem 2.1.** A regular timelike curve  $x(s)$  with curvatures  $k_1 > 0$ ,  $k_2 > 0$  and  $k_3 \neq 0$  is a curve of constant slope if and only if the following condition is satisfied,

$$\left(\frac{k_1}{k_2}\right)^2 + \frac{1}{k_3^2} \left(\left(\frac{k_1}{k_2}\right)'\right)^2 = 1 - \sec^2 \theta = \text{constant}.$$

**Proof.** Let  $x(s)$  be a timelike curve of constant slope. Then for a timelike unit vector  $U$  we have  $g(T, U) = -\cosh \theta$ . Differentiating this equation with respect to  $s$  and using the Frenet formulae we get

$$g(N, U) = 0.$$

Therefore  $U$  is in the subspace  $T - B_1 - B_2$  and can be written as follows

$$U = \alpha T + \beta B_1 + \gamma B_2, \quad (2)$$

where  $\alpha = -\cosh \theta$ ,  $\beta = \sinh \varphi$  and  $\gamma = \sinh \psi$ . In (2)  $\alpha, \beta$  and  $\gamma$  are called as direction cosines of  $U$ . Since  $U$  is unit, we have

$$-\alpha^2 + \beta^2 + \gamma^2 = -1. \quad (3)$$

The differentiation of (2) gives

$$(\alpha k_1 - \beta k_2)N + \left(\frac{d\beta}{ds} - \gamma k_3\right)B_1 + \left(\frac{d\gamma}{ds} + \beta k_3\right)B_2 = 0,$$

and this equation yields

$$\beta = \frac{k_1}{k_2} \alpha = -\frac{1}{k_3} \frac{d\gamma}{ds}, \quad \frac{d\beta}{ds} = \gamma k_3. \quad (4)$$

Since

$$\frac{d\beta}{ds} = \gamma k_3 \quad \text{and} \quad \frac{d\beta}{ds} = \frac{k_3'}{k_3^2} \frac{d\gamma}{ds} - \frac{1}{k_3} \frac{d^2\gamma}{ds^2}$$

we find the second order linear differential equation in  $\gamma$  given by

$$\frac{d^2\gamma}{ds^2} - \frac{k_3'}{k_3} \frac{d\gamma}{ds} + \gamma k_3^2 = 0. \quad (5)$$

If we change variables in the above equation as  $t = \int_0^s k_3(s) ds$  then we get

$$\frac{d^2\gamma}{dt^2} + \gamma = 0,$$

the solution of this equation is

$$\gamma = A \cos \int_0^s k_3(s) ds + B \sin \int_0^s k_3(s) ds, \quad (6)$$

where  $A$  and  $B$  are constants. From (4) and (6) we have

$$A \sin \int_0^s k_3(s) ds - B \cos \int_0^s k_3(s) ds = \frac{k_1}{k_2} \alpha = \beta,$$

$$A \cos \int_0^s k_3(s) ds + B \sin \int_0^s k_3(s) ds = \frac{1}{k_3} \left( \frac{k_1}{k_2} \right)' \alpha = \gamma.$$

From these equations it follows that

$$A = \alpha \left( \frac{k_1}{k_2} \sin \int_0^s k_3(s) ds + \frac{1}{k_3} \left( \frac{k_1}{k_2} \right)' \cos \int_0^s k_3(s) ds \right), \quad (7)$$

$$B = \alpha \left( -\frac{k_1}{k_2} \cos \int_0^s k_3(s) ds + \frac{1}{k_3} \left( \frac{k_1}{k_2} \right)' \sin \int_0^s k_3(s) ds \right), \quad (8)$$

Hence using (3), (7) and (8) we get

$$A^2 + B^2 = \left[ \left( \frac{k_1}{k_2} \right)^2 + \frac{1}{k_3^2} \left( \left( \frac{k_1}{k_2} \right)' \right)^2 \right] \cosh^2 \theta = \cosh^2 \theta - 1,$$

or

$$\left( \frac{k_1}{k_2} \right)^2 + \frac{1}{k_3^2} \left( \left( \frac{k_1}{k_2} \right)' \right)^2 = 1 - \operatorname{sech}^2 \theta = \text{constant}. \quad (9)$$

Conversely, if the condition (9) is satisfied for a regular timelike curve we can always find a constant timelike vector  $U$  which makes a constant angle with the tangent of the curve.

Consider the timelike unit vector defined by

$$U = - \left[ T + \frac{k_1}{k_2} B_1 + \frac{1}{k_3} \left( \frac{k_1}{k_2} \right)' B_2 \right] \cosh \theta.$$

By taking account of the differentiation of (9), differentiations of  $U$  gives that  $\frac{dU}{ds} = 0$ , this means that  $U$  is a constant vector. Therefore the timelike curve  $x(s)$  is a curve of constant slope.

**Theorem 2.2.** A regular timelike curve  $x(s)$  in Minkowski space-time  $E_1^4$  is a curve of constant slope if and only if there exists a  $C^2$ -function  $f$  such that

$$fk_3 = \frac{d}{ds} \left( \frac{k_1}{k_2} \right), \quad \frac{d}{ds} f(s) = -k_3 \frac{k_1}{k_2}. \quad (11)$$

**Proof.** If the timelike curve  $x(s)$  is a curve of constant slope, by Theorem 2.1 we write

$$\left( \frac{k_1}{k_2} \right) \frac{d}{ds} \left( \frac{k_1}{k_2} \right) + \frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) \frac{d}{ds} \left[ \frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) \right] = 0, \quad (12)$$

and hence

$$\frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) = - \frac{\left( \frac{k_1}{k_2} \right) \frac{d}{ds} \left( \frac{k_1}{k_2} \right)}{\frac{d}{ds} \left[ \frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) \right]}. \quad (13)$$

If we write

$$f(s) = - \frac{\left( \frac{k_1}{k_2} \right) \frac{d}{ds} \left( \frac{k_1}{k_2} \right)}{\frac{d}{ds} \left[ \frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) \right]}, \quad (14)$$

then

$$f(s)k_3 = \frac{d}{ds} \left( \frac{k_1}{k_2} \right). \quad (15)$$

From (12) it can be written

$$\frac{d}{ds} \left[ \frac{1}{k_3} \frac{d}{ds} \left( \frac{k_1}{k_2} \right) \right] = -k_3 \frac{k_1}{k_2}. \quad (16)$$

By using (15) and (16) we have

$$\frac{d}{ds} f(s) = -k_3 \frac{k_1}{k_2}. \quad (17)$$

Conversely, let  $f(s)k_3 = \frac{d}{ds} \left( \frac{k_1}{k_2} \right)$ . If we define a timelike unit vector  $U$

by

$$U = - \left( \cosh \theta T + \frac{k_1}{k_2} \cosh \theta B_1 + f(s) \cosh \theta B_2 \right) \quad (18)$$

since the unit tangent  $T$  of  $x(s)$  has a constant angle  $\theta$  with some fixed lines  $l$  directed in the unit timelike vector  $U$ ,  $x(s)$  is a curve of constant slope.

**Theorem 2.3.** A timelike curve  $x(s)$  is a curve of constant slope in Minkowski space-time  $E_1^4$  if and only if

$$\frac{k_1}{k_2} = A \cos \theta + B \sin \theta. \quad (19)$$

**Proof.** Suppose that timelike curve  $x(s)$  is a curve of constant slope in Minkowski space-time  $E_1^4$ . Then the condition in Theorem 2.2 is satisfied.

Let us define  $C^2$ -function  $\theta$  and  $C^1$ -functions  $m(s)$  and  $n(s)$  by

$$\theta(s) = \int_0^s k_3(s) ds, \quad (20)$$

$$\left. \begin{aligned} m(s) &= \frac{k_1}{k_2} \cos \theta - f(s) \sin \theta, \\ n(s) &= \frac{k_1}{k_2} \sin \theta + f(s) \cos \theta. \end{aligned} \right\} \quad (21)$$

If we differentiate equations (21) with respect to  $s$  and take account of (20), (15) and (17) we find that  $m' = 0$  and  $n' = 0$ . Therefore,  $m(s) = A$ ,  $n(s) = B$  where  $A, B$  are constants. Now substituting these in (20) and solving the resulting equations for  $k_1 / k_2$ , we get

$$\frac{k_1}{k_2} = A \cos \theta + B \sin \theta,$$

which is (19).

Finally assume that (19) holds. Then from the equations in (21) we get

$$f = -A \sin \theta + B \cos \theta,$$

which satisfies the conditions of Theorem 2.2. So, the timelike curve  $x(s)$  is a curve of constant slope in Minkowski space-time  $E_1^4$ .

## REFERENCES

- [1] Bonnor, W. B: Null curves in a Minkowski space-time, Tensor, 20, 229-242, 1969.
- [2] Donnan, V., Integral characterizations and the theory of curves, Proc. Amer. Math. Soc., 81 (4), (1981), 600-602.
- [3] Mağden, A., On the curves of constant slope, YYÜ Fen Bilimleri Dergisi, 4, (1993), 103-109.
- [4] Önder, M., Dual timelike normal and dual timelike spherical curves in dual Minkowski space  $D_1^3$ , SDÜ Fen-Edebiyat Fakültesi Fen Dergisi, 1 (1-2), (2006).
- [5] Özdamar, E., and Hacısalıhoğlu H. H., A characterization of inclined curves in Euclidean n-space, Communication de la faculte des sciences de L'Universate d'Ankara, series A1, 24A (1975), 15-22.
- [6] Wong, Y. C., A global formulation of condition for a curve to lie in a sphere, Monatshefte für Mathematik, 67, (1963), 363-365.
- [7] Wong, Y. C., On an explicit characterization of spherical curves, Proceedings of the American Math. Soc., 34 (1972), 239-242.
- [8] Walrave, J., Curves and surfaces in Minkowski space, Doctoral thesis, K. U. Leuven, Fac. Of Science, Leuven, 1995.
- [9] Yaylı Y., Çalışkan A. and Uğurlu H. H., The E. Study Maps of Circles on Dual Hyperbolic and Lorentzian Unit Spheres  $H_0^2$  and  $S_1^2$ , Mathematical Proceedings of the Royal Irish Academy, 102 A (1) (2002), pp. 37-47.